

Turboroundabouts

Multicriterion Assessment of Intersection Capacity, Safety, and Emissions

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A “turboroundabout” is a variation of the conventional multilane roundabout in which spiral road markings and raised lane dividers force drivers to follow a specific path according to their intended destination. This geometry eliminates weaving and cut-in conflicts by guiding drivers continuously from entry to exit. Turboroundabouts were conceived with the main aim of improving safety, but their practical benefits are relatively unknown. Likewise, the few existing studies on turboroundabouts do not allow definitive conclusions to be drawn about the delay and emissions performance characteristics of turboroundabouts; further research is needed. This research focused on the use of appropriate modeling methodologies to understand the effects of turboroundabouts on capacity, safety, and emissions in comparison with the effects of conventional single-lane and double-lane roundabouts. The results indicate that turboroundabouts have capacity levels comparable to those of two-lane roundabouts but are less robust concerning the directional split of the entry traffic; turboroundabouts lead to fewer traffic conflicts, but the traffic conflicts that do occur are more severe. The results also show that the implementation of turboroundabouts provides no advantages for emissions when the main concerns are carbon dioxide and oxides of nitrogen.

A “turboroundabout” is a variation of the conventional multilane roundabout in which drivers are forced to follow a specific path according to their intended destination. The carriageway consists of continuous spiral paths, and curbs are used to separate lanes in the entry, circulatory, and exit zones. The installation of curb dividers has two major benefits: the elimination of conflict points caused by weaving maneuvers and speed reduction because of increased deflection (1). On the negative side, raised curbs make snow removal difficult and may be a risk for motorcyclists (2). The first turboroundabouts were installed in 2000 in the Netherlands. Since then, more than 190 turboroundabouts have been implemented, and the Dutch government no longer constructs multilane conventional roundabouts, having adopted turboroundabouts as the current practice (1). This adoption of turboroundabouts was followed by their adoption in

Poland and, most recently, in Germany, Finland, Norway, and Slovenia (3). Interest in this new layout is also growing in the United States (4).

Turboroundabouts are usually compared with conventional single-lane and two-lane roundabouts at two levels: capacity or delays and safety. A consensus on the results for capacity does not exist. Initial research based on simplified approaches concluded that, in general, turboroundabouts offer a higher capacity than conventional roundabouts of similar size (5, 6). More recent work indicates that the relative performance of turboroundabouts is highly dependent on the demand flows at the major and minor entries (7). A new lane-based capacity method allows quantification of the importance of the directional split at each entry and reveals that only in very specific demand scenarios that are uncommon in real-world networks can a standard turboroundabout be expected to provide more capacity than an equivalent two-lane roundabout (8). This larger capacity happens namely when the proportion of drivers at each entry turning right is abnormally high (usually above 60%).

Researchers have reached greater consensus on the safety benefits of turboroundabouts, despite the lack of quantitative crash data. From a set of before-and-after studies in the Netherlands, Fortuijn concluded that “the measured effect of turboroundabouts on safety is comparable with that of single-lane roundabouts” (1). A study from Mauro and Cattani based on conflict analysis techniques showed a 40% to 50% reduction in the accident rate for turboroundabouts relative to that for two-lane roundabouts (9). Comparison of the number of conflict points—eight in a single-lane roundabout, 24 in a two-lane roundabout, and 14 in a turboroundabout (Figure 1)—also suggests the improved safety of turboroundabouts compared with that of the two-lane roundabout layout.

The safety performance of a roundabout can be related to some measure of its operating speeds (10, 11). In addition to a reduction in the number of conflict points (relative to that in the two-lane roundabout), the turboroundabout design also leads to lower entry and circulating speeds. While drivers can ignore lane markings on a two-lane roundabout and choose an almost direct path while retaining their approach speed, on a turboroundabout, raised splitters force drivers to stay in the correct lane and thus follow paths with smaller radii at lower speeds.

The effect of turboroundabouts on pollutant emissions is also unknown. Research in that field has focused on the emissions impacts of single-lane and multilane roundabouts (12–14). One concern about emissions in turboroundabouts is the extent to which a vehicle’s speed and acceleration–deceleration patterns vary, since drivers are forced to follow a specific path according to their intended

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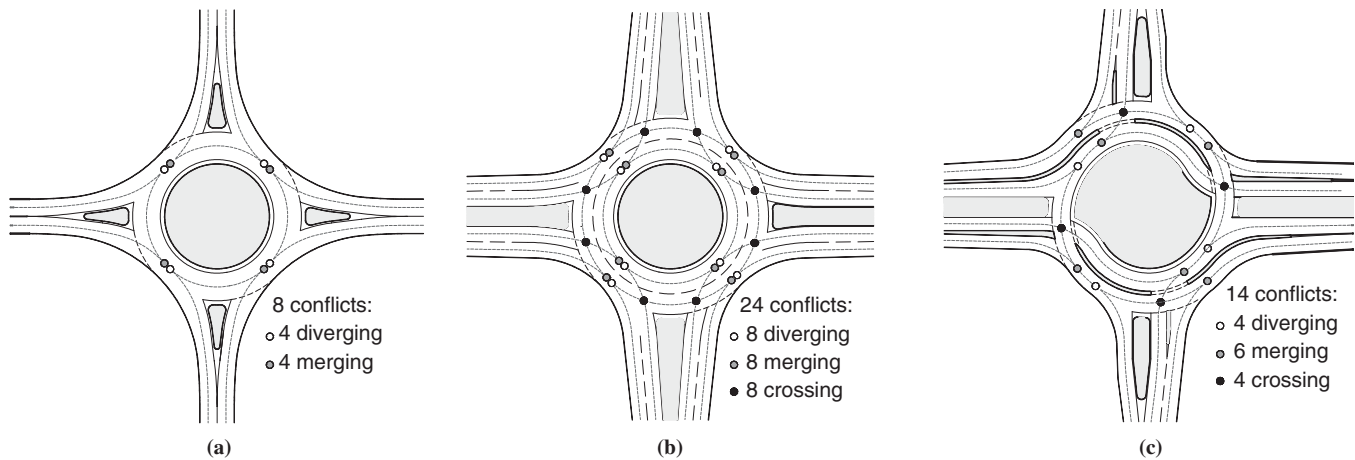


FIGURE 1 Types of conflicts at (a) single-lane roundabouts, (b) two-lane roundabouts, and (c) turboroundabouts.

destination. Such speed variations could have a significant impact on emissions and reduce the potential emissions benefits of the turboroundabout.

From the points presented above, it becomes clear that few studies of turboroundabouts have been conducted and that most studies that have been performed lack solid data from the field and follow different methodologies that in some cases lead to contradictory conclusions. In the absence of crash statistics and emissions data, a deeper analysis is needed. Recent developments in the field of microscopic simulation for safety and emissions analysis suggest that microscopic simulation tools can be successfully used in addition to the classic methods of evaluation of traffic operation and management strategies to evaluate the safety levels, capacity, and emissions of existing and new road infrastructure.

Therefore, the motivation for this research was to use the most appropriate microscopic modeling methodologies to understand the capacity and safety of turboroundabouts and determine emissions from turboroundabouts and then to compare this information with that for conventional single-lane and double-lane roundabouts. The hypothesis is that different patterns of circulating traffic, capacity flows, and lane selection have different effects on emissions and conflict points and, thus, in the relative performance of turboroundabouts. In summary, the objectives of this research were (a) to evaluate capacity and delays, (b) to assess conflict locations and rates of occurrence of conflicts, (c) to quantify the emissions impacts of turboroundabout operations, and (d) to explore the differences between turboroundabouts and conventional single-lane and two-lane roundabouts.

METHODOLOGY

Basic Methodological Approach

The multicriterion assessment described here is based on the use of microsimulation to describe the functioning of alternative, single-lane, two-lane, and turboroundabouts under a number of demand scenarios chosen to represent a wide range of possible real-life situations. An existing single-lane roundabout is taken as a reference problem.

The AIMSUN traffic simulator software package was selected to develop the microsimulation models (15). It provides default simulation outputs that allow the conventional assessment of different

layouts for capacity and delays. AIMSUN also allows the export of full disaggregated trajectory files that can be used by external applications to assess environmental and safety impacts, as described below.

Capacity and Delays

Travel times and delays are considered major performance measures for transportation systems (16). Each layout affects travel times at two levels: through the imposition of different negotiation speeds under free-flow conditions and, mostly, through the provision of different geometric and operational capacity levels. Two measures of performance were initially considered: the average travel time for the whole simulation period and travel time reliability. Some preliminary tests indicated that the variability of travel times is almost independent of the layout, so only the average travel time between origin and destination centroids was considered to measure the operational performance of each alternative.

Safety

The core of this new safety assessment approach is software developed by FHWA [surrogate safety assessment model (SSAM)] (17) that automates conflict analysis by processing vehicle trajectory files produced during the simulation (the vehicle's position, speed, and acceleration profiles). This approach has all the generic advantages of simulation (the ability to assess the safety of new facilities before the occurrence of accidents, the ability to create a controlled testing environment, etc.) but also has some limitations: common microscopic simulation models are developed for traffic-flow analyses and lack some features that are essential for safety analyses (e.g., the ability to analyze overtaking with opposing flow, lateral movement, and U-turns at intersections). Some authors proposed specific procedures to calibrate simulation models for safety assessment (18, 19), but this field of research remains ongoing. The relationship between simulated conflicts and accidents is also not well established. Al-Ghandour et al. found a statically significant relationship between SSAM-predicted conflicts and crashes (predicted by analytic regression methods) but recognized the need for additional studies involving the comparison of SSAM outputs with real crash data (20).

SSAM operates by processing data describing the trajectories of vehicles driving through a traffic facility and identifying conflicts. For each vehicle-to-vehicle interaction, SSAM calculates surrogate measures of safety and determines whether that interaction satisfies the criteria to be deemed a conflict. In the present analysis, the research team used time to collision (TTC) as a threshold to define if a given vehicle interaction is a conflict and the relative speed (DeltaS) as a proxy for accident severity. Their definitions are as follows (21):

- “TTC” is the minimum TTC value observed during the interaction of two vehicles on a collision route. If at any time step the TTC drops below a given threshold [1.5 s in this work, as previously suggested for urban areas (22)], the interaction is tagged a conflict.
- “DeltaS” is the difference in vehicle speeds observed at the instant of the minimum TTC. More precisely, this value is mathematically defined as the norm of the velocity vectors of the two vehicles and thus accounts for the differences in both the absolute speeds and the headings of the vehicles. Further details about alternative surrogate measures can be found elsewhere (23, 24).

Emissions

To estimate vehicle emissions, the vehicle-specific power (VSP) methodology was used (25, 26). This microscopic emissions modeling methodology was chosen because it allows the instantaneous estimation of emissions on the basis of second-by-second vehicle dynamics (speed, acceleration, and slope) and thus takes as input data from the same trajectory files given by AIMSUN (which are also required by the SSAM module). The VSP values are categorized into 14 modes of the engine regime and an emissions factor for each mode is used to estimate emissions of carbon dioxide (CO₂), carbon monoxide (CO), oxides of nitrogen (NO_x), and hydrocarbon (HC) from light-duty gasoline vehicles (engine size <1.4 L), light-duty diesel vehicles (engine size <1.9 L), and light commercial vehicles (engine size <2.5 L). Because of its direct physical interpretation and a strong statistical correlation with vehicle emissions, VSP has proved useful for estimation of microscale emissions for both gasoline vehicles (25, 26) and diesel vehicles (27). Some previous studies have documented the effective use of VSP for analysis of the emissions impacts of single-lane and multilane roundabouts in urban corridors (12–14).

Equation 1 provides the VSP calculation for both light-duty and commercial vehicles (15):

$$\text{VSP} = v \cdot [1.1 \cdot a + 9.81 \cdot \sin(\arctan(\text{grade})) + 0.132] + 0.000302 \cdot v^3 \quad (1)$$

where

VSP = vehicle-specific power (kW/ton),

v = instantaneous speed (m/s),

a = instantaneous acceleration or deceleration (m/s²), and

grade = terrain gradient (decimal fraction).

Total emissions for passenger cars were calculated by use of the assumption that all passenger cars consisted of 45% light-duty gasoline vehicles, 34% light-duty diesel vehicles, and 21% light commercial vehicles (28). Because of the flat terrain, the effect of

road grade was negligible. Total emissions of CO₂, CO, NO_x, and HC by roundabout type were derived on the basis of the amount of time spent in each VSP mode multiplied by its respective emission factor (25–27).

MODEL DEVELOPMENT

Site Selection

In Portugal, the first turboroundabout is expected to be constructed in Coimbra, to replace the existing single-lane Choupal Roundabout (inscribed circle diameter = 57 m, circulating lane width = 7.8 m). This roundabout is one of the main entries to the city, and it occasionally becomes congested during the peak periods. Most legs have one lane both in the entry and in the exit. The east entry has a slip lane toward the north direction. The west leg essentially serves to access a local park and therefore has very low levels of traffic. The speeds on the approach legs are relatively low (≈55 km/h).

It was decided to follow a two-stage implementation. In the first stage, the existing roundabout will be widened and transformed into a conventional two-lane roundabout; in the second stage, after some months to allow driver adaptation, the splitter islands and the inner circle will be reshaped to the final turboroundabout layout (Figure 2).

The two-lane layout was designed according to Portuguese design guidelines (29). Because of some space restrictions, the east and west exits are single lanes; the north and south exits have two lanes for a limited length, and these may be extended in the future. The design of the turboroundabout was based on Dutch guidelines (30, 31).

The simulation area is centered on the intersection and extends roughly 150 m in each direction. This allows simulation of the upstream queues and minimization of the influence of nearby intersections in the simulation outputs.

Traffic Demand

A 24-h period on a typical weekday was chosen as the modeling period to cover a wide range of traffic conditions and to ensure that, regardless of the scenario tested, no vehicles would be retained in the centroids at the end of the simulation period. Traffic flows and speeds at the north and south legs (separately for each direction) were recorded continuously with pneumatic tubes and microwave detectors (Figure 3) and were associated with directional splits observed from video recordings to produce 1-h origin–destination matrices for the whole 24-h period for a total of 23,816 vehicles. The origin–destination matrix, in proportional terms, is reasonably constant during the day, and the incidence of U-turns is negligible. For each entry, the left, through, and right directional splits are as follows: 4%, 61%, and 35%, respectively, for the south entry; 38%, 2%, and 60%, respectively, for the east entry; 43%, 56%, and 1%, respectively, for the north entry; and 30%, 50%, and 20%, respectively, for the west entry.

Currently, the roundabout has spare capacity during most periods. This result happens for several reasons. First, as shown in Figure 4, the demand peaks of the north and east entries do not overlap; second, the slip lane at the east entry allows right turns without opposing traffic; finally, almost no traffic from the south entry goes left or makes U-turns, which facilitates the entries from the north approach.

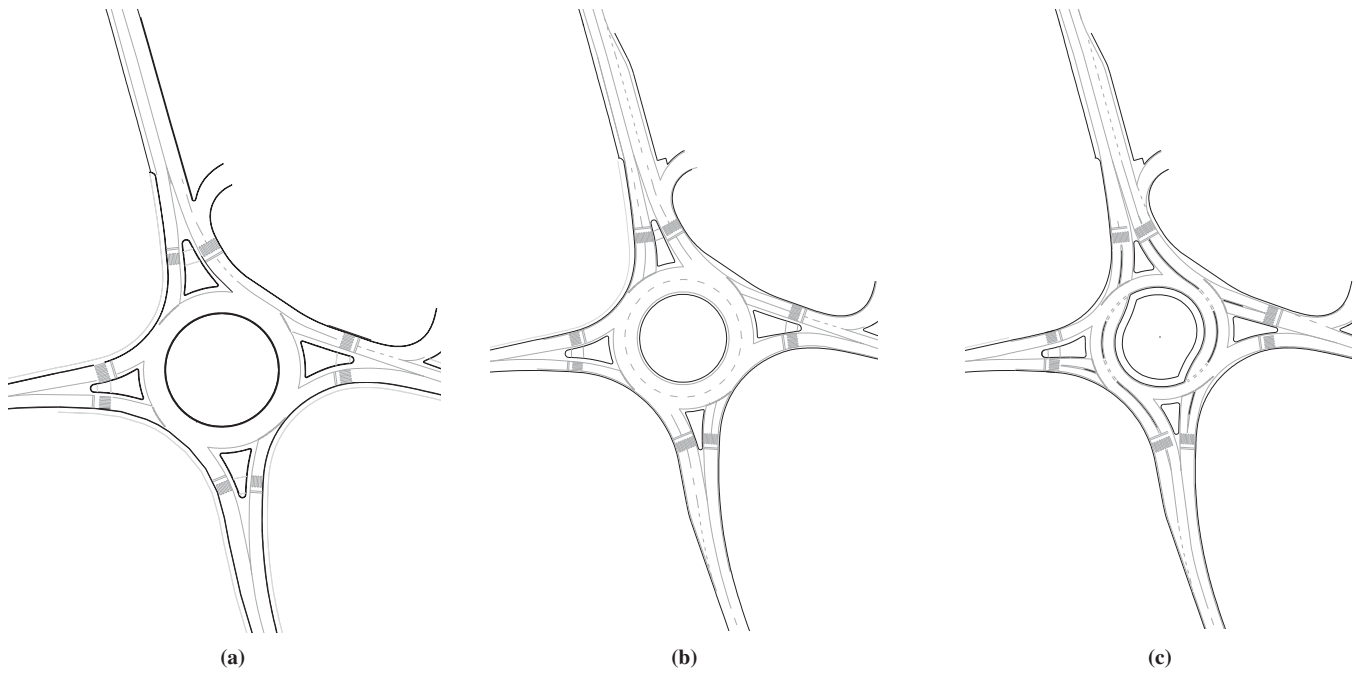


FIGURE 2 Choupal roundabout in Coimbra: (a) existing roundabout layout, (b) proposed two-lane roundabout layout, and (c) turboroundabout layout (north is toward top).

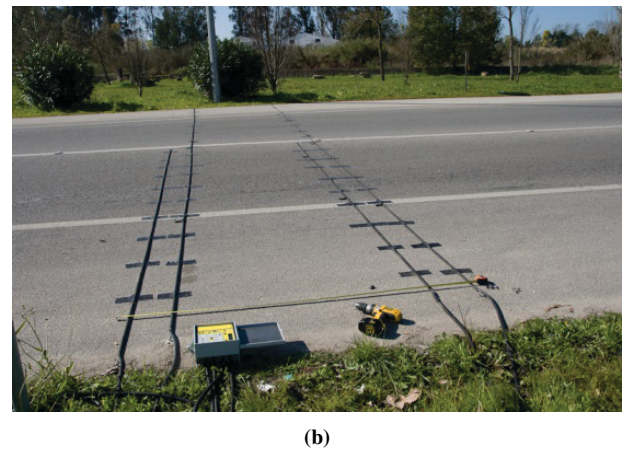
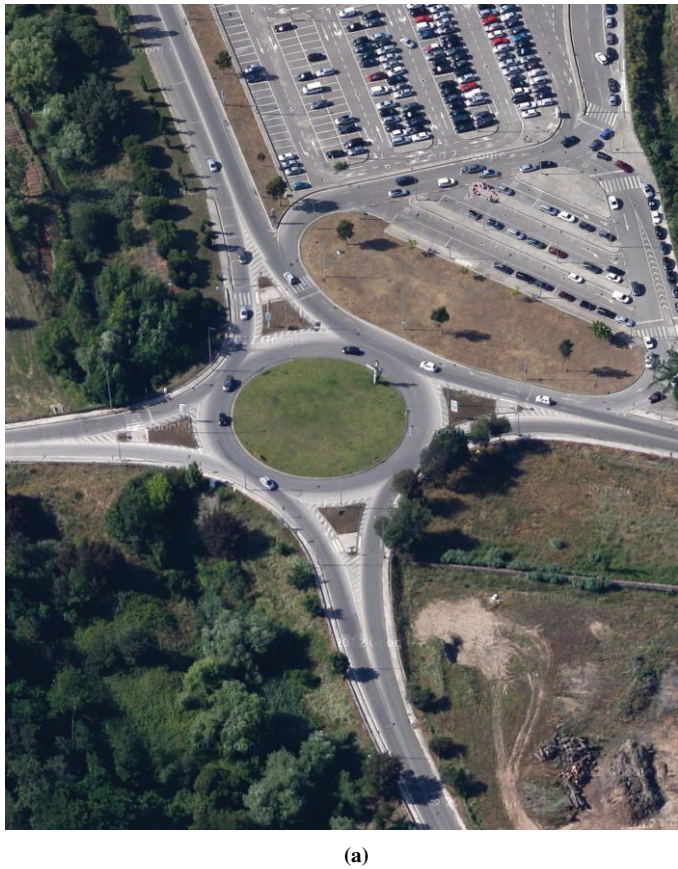


FIGURE 3 Choupal roundabout (Coimbra): (a) aerial view, (b) installation of pneumatic detectors to obtain 24-h flow and speed data, and (c) video recordings to obtain directional splits. [Source for (a): Google Maps.]

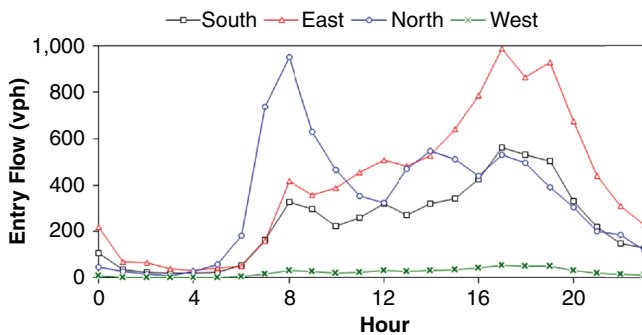


FIGURE 4 Entry flows over 24 h (vph = number of vehicles per hour).

Calibration

The model was calibrated in two steps. The first addressed the parameters of the Gipps car-following model for steady-state operations and consisted of fitting of the model's macroscopic relations to the speed-flow data collected with a microwave sensor. A new methodology that extended previous calibration techniques to properly account for the effect of the drivers' desired speed on the steady-state traffic stream behavior was followed. The second step is mostly related to interrupted flow and driver behavior at intersections (maximum acceleration, normal deceleration, reaction time at stop, and maximum yield time). To optimize these parameters, a procedure based on a genetic algorithm was implemented in Matlab. The objective function of that procedure was minimization of the differences between the observed and simulated density time series in 1-min intervals. The full details of the calibration process are described elsewhere (32).

EVALUATION FRAMEWORK AND RESULTS

Scenarios

The main objective of the evaluation framework was to obtain quantitative measures that allowed identification of the relative merits of each layout. It was assumed that it was important to understand the circumstances under which a layout may be preferable to others more than to obtain accurate absolute performance indicators.

For this task, two main demand scenarios were defined: the first evaluated how the performance indicators changed with increasing traffic demand, if no changes in the directional splits at the entries were assumed; the second evaluated the performance of the different layouts under different directional splits, if no changes in the total entry flow at each entry were assumed.

Capacity and Delays

Because both two-lane conventional roundabouts and turboroundabouts have two lanes per entry, they should each be expected to offer increased capacity compared with that of the existing single-lane layout. However, the capacity differences between the conventional and turboroundabout layouts were not so obvious. Some geometric and functional differences affect capacity. (a) On a normal roundabout, the outer circulatory lane at the major entries (north and south, in the

specific case of the Choupal Roundabout) is used by part of the through traffic movements (east-west and west-east), whereas on a turboroundabout, the opposing traffic is concentrated in a single lane, which reduces the number of large gaps available for vehicles waiting at the yield line. (b) On a normal roundabout, drivers in the right lane of the minor entries are affected by all circulating vehicles, even if the trajectories do not actually intersect (10, 33). On a turboroundabout, the right lane at the minor entries (east and west) is used only to turn right and the opposing traffic is reduced because part of the through traffic (north-south or south-north) is physically separated at the exit. (c) Although right-turning traffic must use the right entry lane on the normal roundabout, both the left and right lanes at the minor entries of a turboroundabout can be used to make that movement.

For the first scenario and for each layout, seven demand levels were simulated, and each one was for a 24-h period. Figure 5a depicts the average travel time (origin to destination) for the first demand scenario. Under the existing demand (global demand factor = 100%), the three geometries operate below capacity and drivers suffer similar delays because of random queuing. The single-lane roundabout is able to receive additional traffic ($\approx 30\%$) before it becomes congested. The two-lane and the turboroundabout layouts continue operating below capacity over the whole range of flows tested.

To test the sensitivity of the delays to the directional splits, the total demand at each entry was assumed to be constant (equal to the observed demand), the traffic split was assumed to be identical for all entries, and the entry proportions were varied in 12.5% steps that covered all possible traffic splits (45 combinations for each layout; for simplicity, no U-turns were considered).

Figure 5b indicates that for all layouts, the minimum travel times are obtained when all vehicles are turning right, and the maximum occurs when all vehicles are turning left, which is related to the increase of the opposing flow at each entry. Both the two-lane and the turboroundabouts are more robust solutions (that is, they allow a wider range of traffic splits without becoming congested), but the conventional two-lane layout operates below capacity for almost every combination tested. These results are consistent with those of a previous work based on analytic gap acceptance formulas in which it was shown that a turboroundabout can be expected to offer more capacity than a two-lane roundabout only if the proportion of right-turning traffic from the minor entries is very high (8).

When the specific case of the Choupal Roundabout is considered, it can be concluded that the conversion to a turboroundabout will maintain the current uncongested operations and will thus have no major effect on actual delays, unless traffic grows significantly or the traffic splits at the entries are drastically changed (in particular, changes that lead to an increase in the number of left turns).

Safety

The effects of both the uniform traffic growth and the directional splits were analyzed at three levels: traffic growth consisting of demand factors of 100% (observed), 130%, and 150% and directional splits of 60-20-20, 20-60-20, and 20-20-60 (in which each set of values indicates the percentages of right-turning, through, and left-turning traffic movements, respectively). Figure 6 illustrates these conflicts for the second demand scenario, the 20-60-20 scenario, indicating the concentration of conflicts at the most heavily congested entries (north and east) and the predominance of weaving conflicts in the two-lane layout.

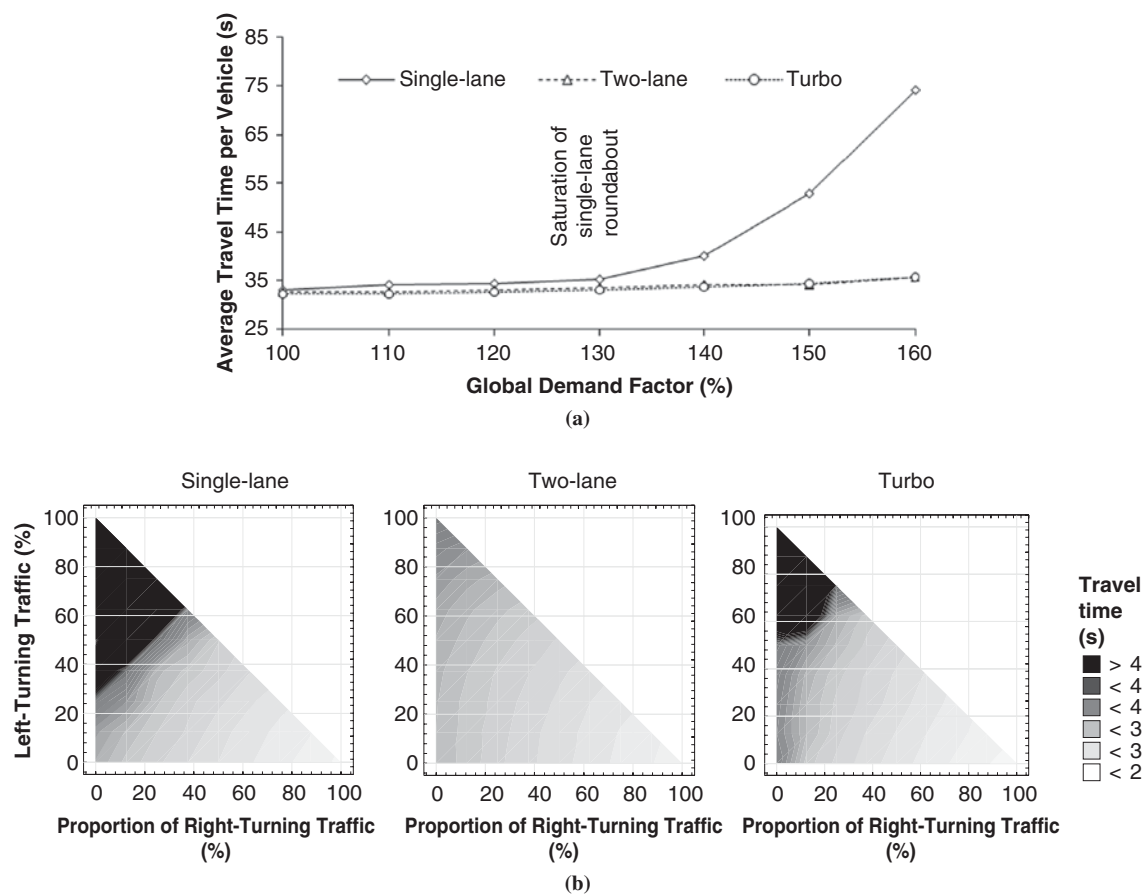


FIGURE 5 Travel times for (a) increasing traffic demand factors and (b) directional splits at entry or entries.

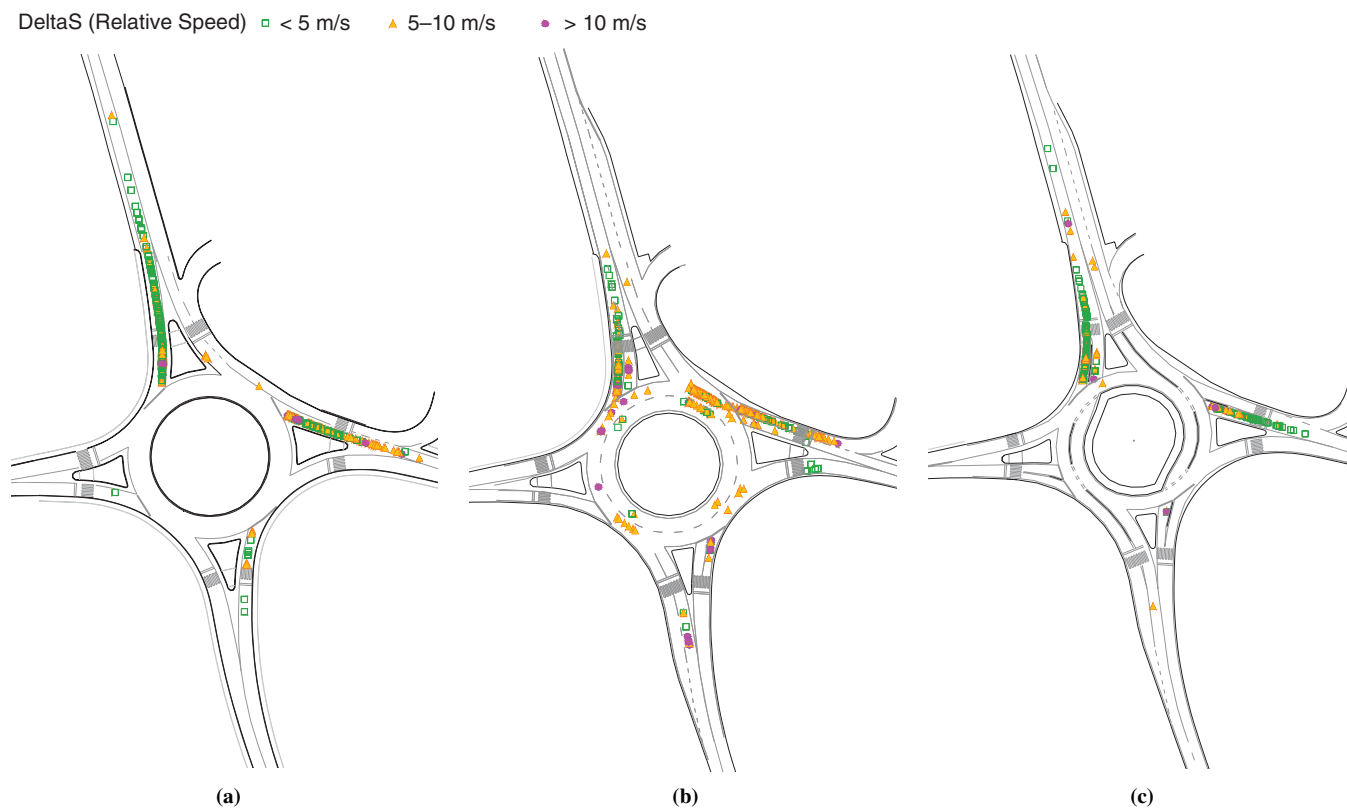


FIGURE 6 Conflict location (20-60-20 scenario).

TABLE 1 Total Number of Conflicts and Average Relative Speeds

Safety Measure	Number of Conflicts			Average Relative Speed (m/s)		
	Single-Lane	2-Lane	Turbo	Single-Lane	2-Lane	Turbo
Demand Factor (%)						
100	143	329	92	6.89	7.75	7.55
130	532	828	288	5.35	7.42	6.49
150	936	1,303	500	4.88	7.42	6.12
Right-Through-Left Directional Split (%)						
60–20–20	145	202	162	5.85	7.24	6.61
20–60–20	752	638	524	5.06	6.78	4.68
20–20–60	1,251	587	650	4.16	5.99	4.39

SSAM outputs are summarized in Table 1. Several conclusions about the effect of total traffic demand can be drawn. (a) As expected, the number of conflicts increases with the total amount of traffic with all layouts; results from additional simulations (not shown here) indicated exponential growth with traffic, which agrees with conventional accident prediction models (34). (b) The two-lane roundabout is the worse solution according to both the number and the severity of conflicts, mostly because of the weaving maneuvers. (c) The turboroundabout has fewer conflicts than the single-lane solution, but the conflicts are more severe because of the increased angle between entry and circulating trajectories.

Table 1 also shows the effect of the directional split at the entry. This set of results also allows some conclusions to be drawn. (a) The number of conflicts tends to increase with the proportion of left-turning traffic, which is related to the increased number of encounters between entering and circulating traffic. However, this relation does not hold for the two-lane roundabout: fewer conflicts occur with the 20–60–20 split scenario than the 20–20–60 split scenario, which suggests that the reduction of weaving and cut-in conflicts at the exits compensates for the increase of rear-end and cut-in conflicts at the entries. (b) The average relative speeds, taken as a surrogate for accident severity, are higher when most vehicles are turning right. Although this result is counterintuitive, it is related to the reduction of the circulating traffic, which allows a higher percentage of vehicles to enter the roundabout at their desired speed and which results in conflicts with the circulating vehicles at higher speeds.

These results agree, in general, with expectations and with data for actual crashes. However, it must be emphasized that SSAM is still an emerging safety assessment method and that the relation between simulated conflicts and real accidents is not yet well determined.

Emissions

This section presents the VSP mode distributions of each roundabout for all scenarios. Furthermore, the impacts of two-lane and turboroundabouts on emissions (CO_2 , CO, NO_x , and HC) are compared with those of the single-lane roundabout.

VSP Mode Distributions

Figure 7 illustrates the percentage of time spent in each VSP mode for each roundabout and all scenarios analyzed. These VSP modes will be used later to estimate the emissions generated for each roundabout.

On average, vehicles spent most of their time in VSP Modes 1, 3, and 4, which correspond to vehicles that decelerate as they approach the roundabout, enter the circulating lanes, and accelerate as they exit the roundabout, respectively. As expected, the percentage of VSP Mode 3 (idling or low-speed situations) increased with the demand factor (Figure 7, *b* and *c*). This increase was particularly noticeable on the single-lane roundabout, whose contributions to VSP Mode 3 was enhanced almost 8% from a scenario of 100% traffic demand to one of 150% traffic demand. It should also be emphasized that vehicles spent less time in VSP Mode 3 in the two-lane roundabout solution than in the turboroundabout solution, but a higher percentage of time was spent in acceleration modes (VSP Modes 4 to 14).

For the directional split scenarios (Figure 7, *d* to *f*), the VSP mode distributions of the three roundabouts were similar when 60% of the vehicles turned right and traveled through. However, when most of the vehicles turned left, significant differences were found. For this scenario, 37% of the time was spent in VSP Mode 3 in a single-lane roundabout. The turboroundabout also achieved a significant increase in VSP Mode 3, namely, compared with that for the two-lane solution. Nevertheless, vehicles spent more time in VSP Modes 4 to 6 in the two-lane roundabout solution, a result that was related to the acceleration modes.

Comparison of Emissions Impacts

This section compares the emission impacts of single-lane, two-lane, and turboroundabouts for different traffic demands and turn rate scenarios.

When the 100% demand factor scenario is considered, significant differences between two-lane and single-lane roundabouts were observed (Table 2). The introduction of the two-lane conventional roundabout could save up to 17% for both CO_2 and NO_x emissions and 21% for CO emissions. The turboroundabout was a particularly effective means to reduce local pollutant emissions: it led to average CO and HC emissions reductions of 24% and 33%, respectively. This reduction was explained by the fact that the lowest acceleration and deceleration rates were experienced by drivers on the turboroundabout (Figure 7a), and the result was especially relevant for CO emissions.

For the 150% demand factor scenario, the difference in the amounts of emissions among the three types of roundabouts increased compared with the amounts obtained by use of the lower demand factors. In fact, the two-lane roundabout yielded the highest reductions in

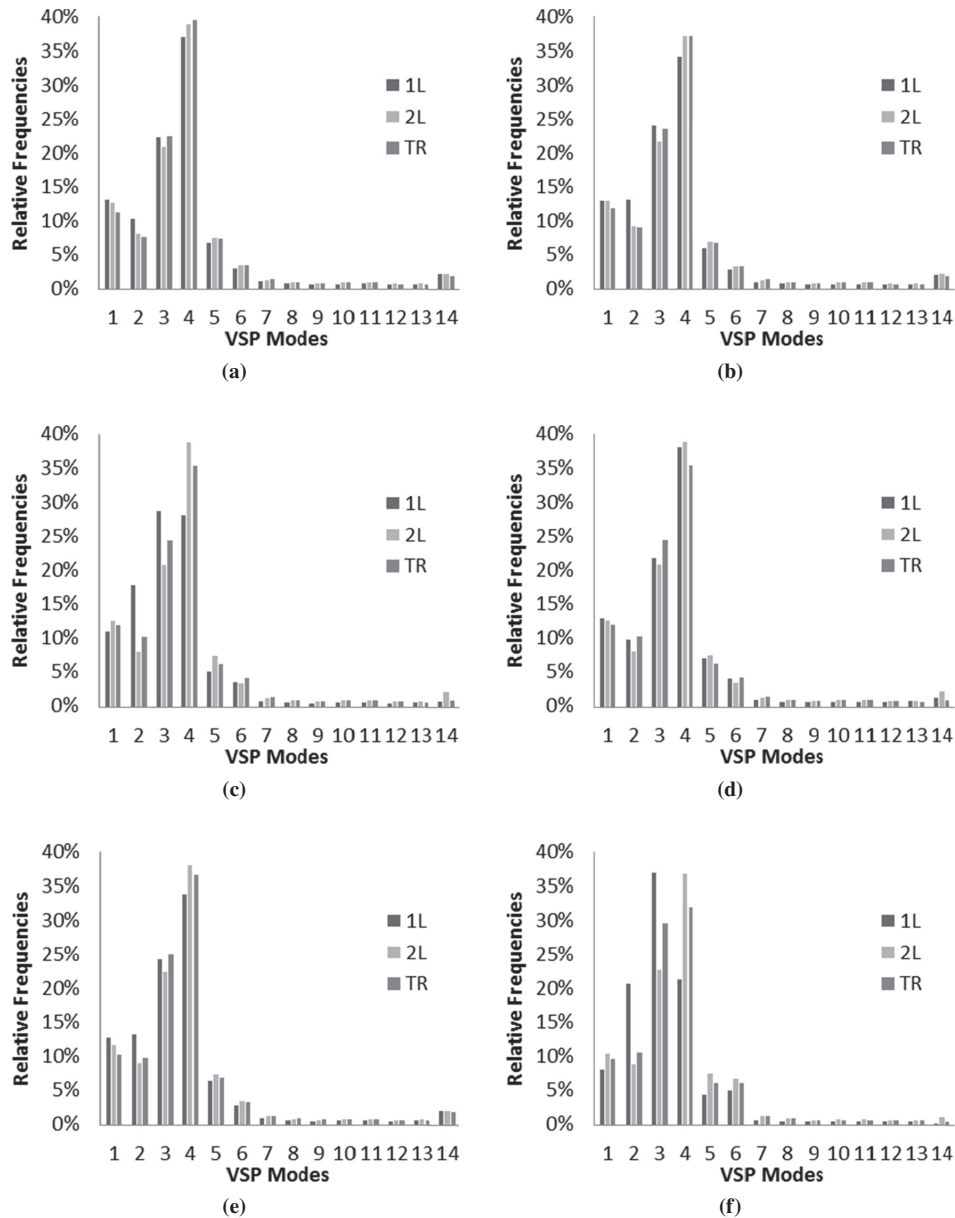


FIGURE 7 Total amount of time spent in each VSP mode (relative frequency) for each roundabout and different levels of traffic flow and different turn ratios: (a) 100% demand factor, (b) 130% demand factor, (c) 150% demand factor, (d) 60–20–20 distribution scenario, (e) 20–60–20 distribution scenario, and (f) 20–20–60 distribution scenario (1L = one-lane roundabout; 2L = two-lane roundabout; TR = turboroundabout).

CO₂ and NO_x emissions: 21% and 18%, respectively. On the basis of the reductions in CO and HC emissions in the 150% demand factor scenario, the results indicate that the turboroundabout is the better environmental solution (18% reduction for CO emissions and 34% reduction for HC emissions).

For the directional split scenarios, the results showed that if 60% of approaching vehicles turned right, they emitted less CO₂ in the two-lane roundabout than in the other roundabouts. Analyses of the remaining directional split scenarios (the 20–60–20 and 20–20–60 scenarios) resulted in the same conclusions obtained for the two-lane roundabout. As displayed in Figure 5, the turboroundabout offers less capacity than the two-lane roundabout when no traffic turns right and particularly when vehicles want to turn left (20–20–60 scenario).

At the emissions level, the results obtained also confirmed these findings.

The differences in CO₂ emissions between the two-lane roundabout and the turboroundabout were larger for low rates of right-turning vehicles. When 60% of vehicles went through and turned left, they produced an amount of CO₂ up to 6% greater in the turboroundabout than in the two-lane roundabout. If it is assumed that all movements are made to the right, this difference decreases to 3%. When the results between two-lane and turboroundabouts are compared, NO_x emissions followed the same trend found for CO₂ emissions, which means that the implementation of a turboroundabout does not lead to reductions in the amounts of these two gases. Nonetheless, CO and HC emissions savings on the turboroundabout were more significant

TABLE 2 Variation of Emissions by Roundabout Type

Safety Measure	Roundabout Type	Emissions			
		CO ₂ ^a	CO ^a	NO _X ^a	HC ^a
Demand Factor (%)					
100	Single-lane (kg)	3,001.21	20.44	9.29	0.58
	2-lane (%)	-17	-21	-17	-20
	Turbo (%)	-15	-24	-16	-33
130	Single-lane (kg)	3,886.40	25.73	11.92	0.75
	2-lane (%)	-15	-15	-14	-17
	Turbo (%)	-14	-19	-14	-31
150	Single-lane (kg)	4,800.46	29.86	14.49	0.93
	2-lane (%)	-21	-15	-18	-22
	Turbo (%)	-19	-18	-17	-34
Right-Through-Left Directional Split (%)					
60–20–20	Single-lane (kg)	2,576.73	13.06	7.41	0.45
	2-lane (%)	-11	-13	-10	-13
	Turbo (%)	-8	-11	-7	-26
20–60–20	Single-lane (kg)	2,899.02	18.81	8.81	0.56
	2-lane (%)	-14	-15	-13	-17
	Turbo (%)	-8	-14	-8	-27
20–20–60	Single-lane (kg)	3,751.45	18.05	10.71	0.69
	2-lane (%)	-29	-7	-23	-29
	Turbo (%)	-23	-13	-20	-38

^aPercentages represent variations in emissions in relation to those for single-lane roundabout for all scenarios during a 24-h period.

(-13% and -38%, respectively) in the 20–20–60 directional split scenario.

CONCLUSIONS

This research explored the effect of turboroundabouts on capacity, conflict locations, and the emissions generated from vehicles. A microscopic simulation approach was followed to identify the consequences of the conversion of an existing single-lane roundabout to a two-lane roundabout and then to a turboroundabout.

The results indicated no relevant differences in travel times when the roundabout is operating below capacity levels and then when it undergoes a fast increase in capacity. The single-lane roundabout offers the least capacity. Both the two-lane and turboroundabouts have two entry lanes per approach and thus offer additional capacity. Drivers on a conventional two-lane roundabout have more flexibility to select the entry lane, which allows a wider range of traffic splits before congestion occurs. Turboroundabouts offer more capacity than two-lane roundabouts only under specific and rare demand scenarios, namely, when the proportion of right turns at the minor entries is abnormally high (above 60%).

The SSAM methodology was followed to estimate the safety of the three alternatives. The two-lane roundabout was the worst solution according to both the number and the severity of conflicts, mostly because of the weaving and cut-in maneuvers. The turboroundabout had fewer conflicts than the single-lane roundabout, but the conflicts were more severe because of the increased angle between the entry and circulating trajectories.

The total emissions of vehicles moving through the roundabout were further compared. This study used the VSP methodology, which takes into account speed trajectories from the AIMSUN model, to estimate the second-by-second emissions generated from vehicles

during different acceleration–deceleration cycles. The results showed that turboroundabouts produced more CO₂ and NO_x emissions than did the two-lane roundabouts; thus, the implementation of turboroundabouts offers no advantage if the major concern in a certain region is related, for instance, to NO_x pollution levels. If the priority is the reduction of CO₂ emissions, a two-lane roundabout is a better choice, but for other local pollutants (CO and HC), the turboroundabout offers an advantage.

Overall, it becomes clear that when it is necessary to implement a two-lane roundabout as an alternative to a single-lane one, commonly because of capacity considerations, a turboroundabout is probably the best option, unless a maximum output capacity is needed.

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